







Ditec ION4-ION6 Sliding gates (translation of the original instructions)

Technical manual

Contents

Declara	l safety precautions	4
1.	Caractéristiques techniques	د د
1.1	Operating instructions	7
1.2	Machinery Directive	7
2.	Standard installation	
3.	Dimensions	
4.	Main components	
4. 5.	Installation	7
5.1	Preliminary checks	
5.2	Base plate position.	10
5.3	Gearmotor installation	1
5.4	Rack installation	12
5.5	Operation with virtual encoder	12
5.6	Installation of optional accessories.	13
5.6.1	Magnetic limit switches	
6.	Electrical connections	
7.	LCU48 card	1!
7.1	ION4-6 parallel installation layout	
8.	Using of the menus	1'
8.1	Switching the display ON and OFF	1
8.2	Navigation keys	1
8.3	Menu map	
9.	Product start-up	20
9.1	WZ configuration wizard menu	
10.	Commands	2
10.1	SOFA1-SOFA2 or GOPAVRS self-controlled safety edge	23
11.	Outputs and accessories	2
12.	Jumper setting	24
13.	Adjustments	2
13.1	Main menu	2
13.2	Second level menu - AT (Automatic Configurations)	2
13.3	Second level menu - BC (Basic Configurations)	2'
13.3.1 13.4	Additional BC level parameters that can be configured (available with $\rightarrow \rightarrow \rightarrow$	28
13.4.1	Additional BA level parameters that can be configured (available with $\square T \rightarrow \square$ enabled)	2:
13.5	Second level menu - RO (Radio Operations)	32
13.5.1	Additional RO level parameters that can be configured (available with \square \square \rightarrow \square enabled)	30
13.6	Second level menu - SF (Special Functions)	34
13.6.1	Additional SF level parameters that can be configured (available with $H \rightarrow H$ enabled)	35
13.7 13.7.1	Additional CC level parameters that can be configured (available with \Box $T \rightarrow \Box$ \Box enabled)	პი
13.8	Second level menu - FM [Fnerry Management]	3'
13.8.1	Additional EM level parameters that can be configured (available with \square \square \square \square enabled)	38
13.9	Second level menu - AP (Advanced Parameters)	38
13.9.1	Second level menu - AT (Automatic Configurations) Second level menu - BC (Basic Configurations) Second level menu - BA (Basic Configurations) Second level menu - BA (Basic Adjustment) Second level menu - BA (Basic Adjustment) Additional BA level parameters that can be configured (available with \(\begin{array}{ccc} \begin{array}{cccccccccccccccccccccccccccccccccccc	40
14.1	Display of automation status	42
14.2	Display of safety devices and commands	44
14.3	Visualisation of alarms and faults	
15.	Troubleshooting	48

Key



This symbol indicates instructions or notes regarding safety, to which special attention must be paid.

i

This symbol indicates useful information for the correct functioning of the product.

General safety precautions



ATTENTION! Important safety instructions. Please follow these instructions carefully. Failure to observe the information given in this manual may lead to severe personal injury or damage to the equipment. Keep these instructions for future reference.

This manual and those for any accessories can be downloaded from www.ditecautomations.com

This installation manual is intended for qualified personnel only • Installation, electrical connections and adjustments must be performed by qualified personnel, in accordance with Good Working Methods and in compliance with the current regulations • Read the instructions carefully before installing the product. Wrong installation could be dangerous • Before installing the product, make sure it is in perfect condition.

The packaging materials (plastic, polystyrene, etc.) should not be discarded in the environment or left within reach of children, as they are a potential source of danger • Do not install the product in explosive areas and atmospheres: the presence of inflammable gas or fumes represents a serious safety hazard • Make sure that the temperature range indicated in the technical specifications is compatible with the installation site • Before installing the motorization device, make sure that the existing structure, as well as all the support and guide elements, are up to standards in terms of strength and stability. Verify the stability and smooth mobility of the guided part, and make sure that no risks of fall or derailment subsist. Make all the necessary structural modifications to create safety clearance and to guard or isolate all the crushing, shearing, trapping and general hazardous areas • The motorization device manufacturer is not responsible for failure to observe Good Working Methods when building the frames to be motorized, or for any deformation during use • The safety devices (photocells, safety edges, emergency stops, etc.) must be installed taking into account the applicable laws and directives, Good Working Methods, installation premises, system operating logic and the forces developed by the motorized door or gate • The safety devices must protect against crushing, cutting, trapping and general danger areas of the motorized door or gate. Display the signs required by law to identify hazardous areas • Each installation must bear a visible indication of the data identifying the motorized door or gate • Before connecting the power supply, make sure the plate data correspond to those of the mains power supply. An omnipolar disconnection switch with a contact opening distance of at least 3 mm must be fitted on the mains supply. Check that there is an adequate residual current circuit breaker and a suitable overcurrent cutout upstream of the electrical installation in accordance with Good Working Methods and with the laws in force • When requested, connect the motorized door or gate to an effective earthing system that complies with the current safety standards • Before commissioning the installation to the end user, make sure that the automation is adequately adjusted in order to satisfy all the functional and safety requirements, and that all the command, safety, and manual release devices operate correctly.

During maintenance and repair operations, cut off the power supply before opening the cover to access the electrical parts • The protection cover of the operator must be removed by qualified personnel only.

The electronic parts must be handled using earthed antistatic conductive arms. The manufacturer of the motorization declines all responsibility if component parts not compatible with safe and correct operation are fitted • Only use original spare parts for repairing or replacing products • The installer must supply all information concerning the automatic, manual and emergency operation of the motorized door or gate, and must provide the user with the operation and safety instructions.

Declaration of incorporation of partly completed machinery (Directive 2006/42/EC, Annex II-B)

We, ASSA ABLOY Entrance Systems AB Lodjursgatan 10

SE-261 44 Landskrona Sweden.

declare, under our sole responsibility, that the type of equipment with the name:

Ditec ION4-6 automation for swing gates

Complies with the following directives and their amendments:

2006/42/EC Machinery Directive (MD), regarding the following essential health and safety requirements: 1.1.2, 1.1.3, 1.2.1, 1.2.2, 1.2.3, 1.2.4.2, 1.2.6, 1.3.9, 1.4.3, 1.7.2, 1.7.3, 1.7.4, 1.7.4.1, 1.7.4.2

2014/30/EU Electromagnetic Compatibility Directive (EMCD)

2014/53/EU Radio Equipment Directive (RED)

2011/65/EU Restriction of Hazardous Substances (RoHS 2)

2015/863/EU Restriction of Hazardous Substances (RoHS Amendment 2)

Harmonised European standards which have been applied:

EN 61000-6-3:2007 + A1:2011 + AC:2012 EN 61000-6-2:2019

EN 60335-1:2012 + AC:2014 + A11:2014 + A13:2017 + A1:2019 + A14:2019 + A2:2019 + A15:2021

EN 60335-2-103:2015

EN 62233:2008 + AC:2008 EN ISO 13849-1:2015 ETSI EN 300 220-2 V3.2.1 ETSI EN 300 220-1 V3.1.1 ETSI EN 301 489-1 V2.2.3 ETSI EN 301 489-3 V2.1.1

Other standards or technical specifications which have been applied:

IEC 60335-1:2010 + C1:2010 + C2:2011 + A2:2013 + C1:2014 + A2:2016 + C1:2016

IEC 60335-2-103:2006 + A1:2010 EN 12453:2017

The manufacturing process guarantees that the equipment complies with the technical documentation.

Do not put equipment into service until the installed finished Automatic Entrance System has been declared compliant with Directive 2006/42/EC on Machinery.

Responsible for the technical documentation:

Matteo Fino Ditec S.p.A. Largo U. Boccioni, 1 21040 Origgio (VA) Italy

Signed on behalf of ASSA ABLOY Entrance Systems AB by:

Place Date Signature Position
Origgio 2023-09-07 Matteo Fino CEO Ditec

UK Declaration of Conformity

We:

ASSA ABLOY Entrance Systems AB Lodjursgatan 10 SE-261 44 Landskrona Sweden

Declare under our sole responsibility that the types of equipment with names:

Ditec ION4-6 automation for swing gates

Complies with the following directives and their amendments:

- Supply of Machinery (Safety) Regulations 2016
- Electromagnetic Compatibility Regulations 2016
- Radio Equipment Regulations 2017
- The Restriction of the Use of Certain Hazardous Substances in Electrical and Electronic Equipment Regulations 2012 (RoHS)

Harmonized European standards that have been applied:

EN 61000-6-3:2007 + A1:2011 + AC:2012 EN 61000-6-2:2019

EN 60335-1:2012 + AC:2014 + A11:2014 + A13:2017 + A1:2019 + A14:2019 + A2:2019 + A15:2021

FN 60335-2-103-2015

EN 62233:2008 + AC:2008 EN ISO 13849-1:2015 ETSI EN 300 220-2 V3.2.1 ETSI EN 300 220-1 V3.1.1 ETSI EN 301 489-1 V2.2.3 ETSI EN 301 489-3 V2.1.1

Other standards or technical specifications that have been applied:

IEC 60335-1:2010 + C1:2010 + C2:2011 + A2:2013 + C1:2014 + A2:2016 + C1:2016

IEC 60335-2-103:2006 + A1:2010 EN 12453:2017

The manufacturing process ensures the compliance of the equipment with the technical file.

Responsible for technical file:

Matteo Fino Ditec S.p.A. Largo U. Boccioni, 1 21040 Origgio (VA) Italy

Signed for and on behalf of ASSA ABLOY Entrance Systems AB by:

Place Date Signature
Origgio 2023-09-07 Matteo Fino

Position

CEO Ditec

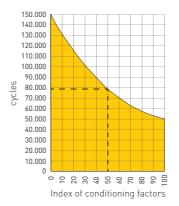
1. Caractéristiques techniques

	Ditec ION4	Ditec ION4J	Ditec ION6	Ditec ION6J
Maximum stroke		12	m	
Maximum gate weight	400	kg	600) kg
Gate speed		0,1÷0,	3 m/s	
Thrust	200 N nominaux, 60	00 N de démarrage	300 N nominaux, 8	00 N de démarrage
Power supply	230 V~ 50/60 Hz	120 V~ 50/60 Hz	230 V~ 50/60 Hz	120 V~ 50/60 Hz
Power absorption	0,45 A	0,9 A	0,6 A	1,2 A
Fuse	T1A	F2A	F1,6A	F3,15A
Power	100) W
Service class		FRÉQ (testé jusqu'à ´		
Intermittence		S2= 30 mir S3= 60%		
Cycles / day *		800 (T=	- 25°C)	
Continuous cycles *		30 (T=	25°C)	
Lifespan	De 50 000 à 150 000 cycles en fonction des conditions reportées dans le tableau (voir instructions complètes).			
Usage temperature (T)	-20°C	+55°C -35°C	with active	NIO)
Degré de protection		IP	44	
Motor output		24V 1	0A max	
Power supply to accessories		24V 0	,3A max	
Control panel		LCU	J48	
Radio frequency	433,92 MHz (cod. ZENRS) 868,35 MHz (cod. ZENPRS)	ZENRS reco	eiver module incl	uded, ZENPRS
Storable radio codes		100 = (
Noise level L _{PA}		≤70 d	B (A)	

^{*} Indicative cycles considering a 6 m wing and factory settings (default speed of 20 cm/s). ION4 / ION6 allows a maximum speed of 30 cm/s (configurable). A cycle is considered an opening followed by a closing.

Index of conditioning factors				
		ION4	ION6	
	>150Kg	10	-	
Gate wing weight	>200Kg	20	10	
date wing weight	>300Kg	30	20	
	>400Kg	-	30	
Gate wing width	>4m	20	10	
date wing width	>8m	-	20	
Wheel diameter <1	1	0		
Saline environment			0	
Safety edge installed			0	
R1/R2 > default	1	0		
VA/VC > default OC/CB < default	1	0		

Example of lifespan calculation for ION4		
Gate wing weight>150Kg	10	
Gate wing width> 4.5m	10	
Dust	10	
Safety edges installed	10	
VA/VC > default	10	
Total stress index 50		
Estimated lifespan - 80,000 cycles		
Estimated daily cycles 22 (for 10 years)		



1.1 Operating instructions

Use: FREQUENT for condominium, industrial and commercial, car park entrances with heavy driveway or pedestrian use.

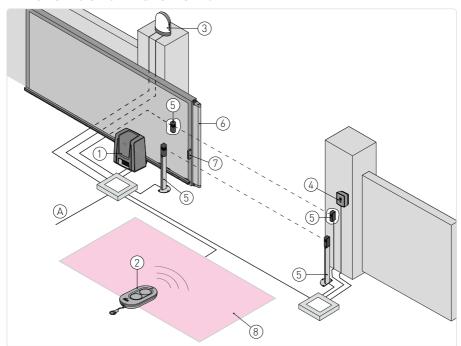
- The class of service, usage times and number of consecutive cycles are suggestions. They are statistically measured under average usage conditions and cannot be certain for every single case.
- For each automatic entrance, there are variables such as friction, balancing and environmental conditions that can substantially change the operating life and quality of the automatic entrance or some of its components (including the automated mechanisms). It is up to the installer to implement safety factors appropriate for each particular installation.

1.2 Machinery Directive

According to the Machinery Directive (2006/42/EC), the installer who motorises a door or gate has the same obligations as the manufacturer of a machine, and as such must:

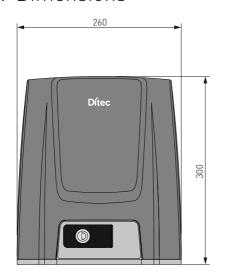
- prepare the technical documentation, which must contain the documents indicated in Annex V of the Machinery Directive;
- (the technical documentation must be kept and made available to the competent national authority for at least ten years, starting from the date of construction of the motorised door);
- draw up the EC statement of conformity according to Annex II-A of the Machinery Directive and hand it over to the customer;
- affix the CE marking to the motorised door in accordance with point 1.7.3 of Annex I of the Machinery Directive.

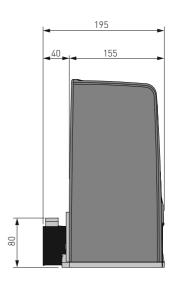
2. Standard installation



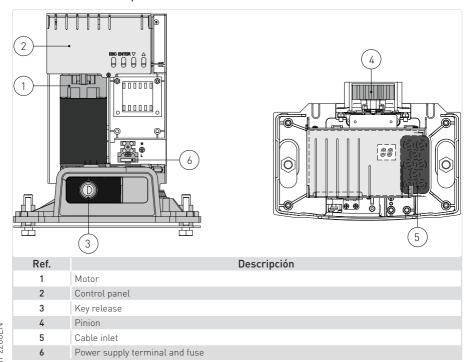
Ref.	Code	Description	Cable		
1	Ditec ION4 - ION6	Actuator ION with control panel	3G x 1.5 mm²		
Α		Connect the power supply to a type-approved omnipolar switch, with a contact opening distance of at least 3mm (not supplied). See chapter 6. The connection to the mains must follow an independent path, separate from the connections to the control and safety devices.			
2	ZEN	Transmitter	/		
	FLM	Flashing light	2 x 1 mm ²		
3	FL24	Antenna (integrated in the flashing light)	RG-58 coax cable (50 Ω)		
	AXK4	Digital combination wireless keypad	/		
4	AXK5M AXK5N AXK5NM AXK5NI	Wall-mounted key-operated selector switch with European cylinder Semi-recessed key-operated selector switch with European cylinder Wall-mounted key-operated selector switch without cylinder Semi-recessed key-operated selector switch without cylinder			
	AXR7	RFID reader unit	5 x 0.5 mm ²		
5	LIN2 LIN2B AXP2 LAB4	Photocells	4 x 0.5 mm²		
6	SOFAP20 SOF2M20-SOF3M20 SOFA15-SOFA20- SOFA25	Safety edge	2 x 0,5 mm² min		
7	GOPAV	Radio system for sensitive edges	/		
8	LAB9	Magnetic loop	2 x 1,5 mm ²		

3. Dimensions





4. Main components



IP2288EN

5. Installation

The given operating and performance features can only be guaranteed with the use of DITEC accessories and safety devices.

Unless otherwise specified, all measurements are expressed in mm.

5.1 Preliminary checks

Check the stability of the wing (derailing and lateral falls) and the sliding wheels and that the upper quides do not cause any friction.

The sliding guide must be securely fixed to the ground for the full length within doorway and must have no irregularities that could hinder the movement of the wing.

The opening and closing stops must be fitted.

If the gate has slits, make sure they are covered to prevent shearing points or install active safety edges on the columns.

Safety device should be installed at the end of the wing to reduce the collision force.



WARNING:

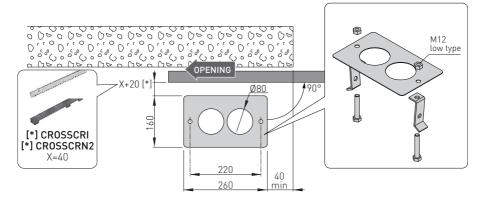
- •Make sure that the gate can not exit the sliding guides and fall.
- •Make sure that the protection system and any manual release function correctly.

5.2 Base plate position

Make a concrete base with the anchor ties and base plate embedded, which must be level and clean and of the size indicated in the figure.

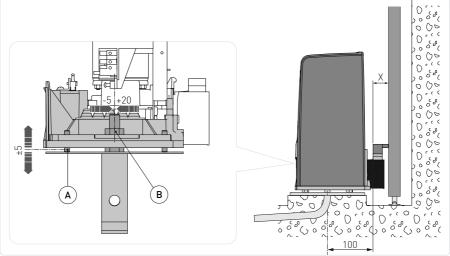


NOTE: if the concrete base has already been made, base plate can be fixed using M8 plugs (not supplied).



5.3 Gearmotor installation





- Release the gearmotor [1] (see OPERATING INSTRUCTIONS). Loosen the front screw [2] and remove the casing by pressing on its sides [3-4].
- Place the gearmotor on the base plate.
- Adjust the gearmotor horizontally by sliding it along the slots of the gearmotor base and vertically with four levelling screws [A].

NOTE: during the vertical adjustment, keep the gearmotor slightly raised from the base plate so that the rack can be fixed and subsequent adjustments are possible.

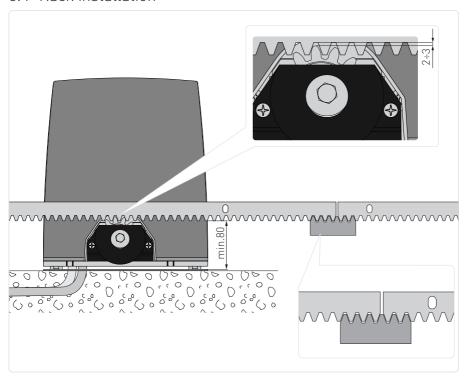
- After adjusting, fix the gearmotor using screws [B].



P2288EN

WARNING: The gearmotor must be suitably raised from the ground to avoid flooding. Tighten the [B] screws using a tightening torque of 20-25 Nm.

5.4 Rack installation



- Release the gearmotor (see OPERATING INSTRUCTIONS) and open the gate.
- Place the rack against the pinion and sliding the gate manually fix it along its whole length.
 NOTE: To make it easier to align the rods correctly, use a scrap piece of rack and rest it underneath the junction point, as shown in the figure detail.
- Once fixed, vertically adjust the gearmotor to give a play of about 2 to 3 mm between the pinion and the rack.
- Secure the gearmotor with the [B] screws using a tightening torque of 20-25 Nm.
- Slightly lubricate the rack and pinion after assembly.
 Manually check that the gate slides evenly and without friction.

5.5 Operation with virtual encoder

ION4-ION6 gearmotors do not require limit switches because they have a virtual encoder.

Mechanical opening and closing end stops must be installed.

The gate automatically slows when approaching the end stops.

WARNING: when the gate reaches the opening or closing limit stop, it reverses briefly to facilitate manual release of the gearmotor.

5.6 Installation of optional accessories

5.6.1 Magnetic limit switches



The limit switch kit is used to stop the gate before it reaches the opening and closing mechanical stops.

With a limit switch installed, slowdown is carried out at regulated power to overcome possible friction.

For the installation of the limit switch kit, refer to the **NES100FCM** manual.

To position the limit switches, you can use the menu $\Sigma F \to TF$ (visible by activating the additional configurations $\Pi T \to \Pi \Pi$).

The display shows the status of the limit switches:

- FA: opening limit switch configured and activated;
- **F**[: closing limit switch configured and activated;
- Na (both parts of display active): opening limit switch not configured and activated;
- No (no part of display active): closing limit switch not configured and activated;
- [. (central part of display active): no limit switch activated.

With the limit switches configured as STOP [$\mathbf{FA} = SX$; $\mathbf{FC} = SX$] the anti-violation function is activated. When the automation stopped open or closed, if the gate backs off releasing the limit switch, it is brought back into position avoiding openings from external forces [energy saving must be disabled $\mathbf{ES} = \mathsf{OFF}$].

5.6.2 Battery kit

For installation of the battery kit, refer to the SBU-IONSBU-BBU20-BBU65 (IP2254) manual.



The battery kit guarantees operation if there is a power cut. For advanced control of battery-powered operation, refer to the EM menu.

5.6.3 Remote release handle

For installation of the remote release handle, refer to the IONSBM and ASR2 manual.

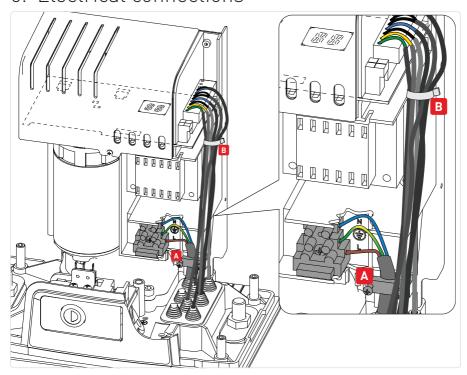


The kit can be used to remotely release the gearmotor.

A microswitch quarantees safety.

When the handle is released, the control panel performs a reset

6. Electrical connections



Before connecting the power supply, make sure that the data on the plate correspond to the electricity distribution network data. Provide an omnipolar switch/disconnector on the power network with a contact opening distance of 3 mm or more. Check that there is a suitable residual-current device and surge protector upstream of the electrical system. Use an H05RN-F 3G1.5 electrical cable and connect it to terminals L (brown) and N (blue) inside the automation system. Connect the earth cable 4 (yellow/green) to the earth terminal.



ATTENTION: always observe L-N polarity when connecting to the mains and close all unused clamps.

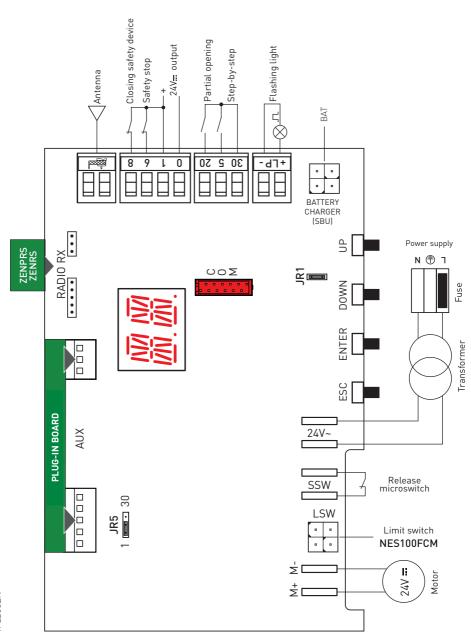
Secure the cable by means of the cable clamp and only unsheathe it at the terminal.

Connections to the electrical distribution network and any other low-voltage conductors [230 V], in the section outside the automation system, must be made with corrugated pipes that are independent and separate from the path of connections to the control and safety devices [SELV= Safety Extra Low Voltage]. Make sure there are no sharp edges that could damage the power cord.



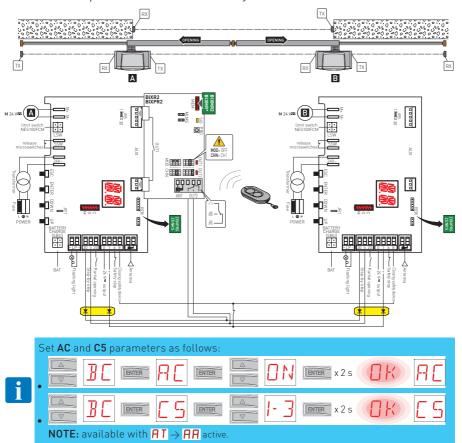
Ensure that the mains connection cables, any other low-voltage cables (230 V), and safety extra-low voltage safety accessory connection cables in the portion located inside the product are kept well separated from the gear motor body.

7. LCU48 card



IP2288EN

7.1 ION4-6 parallel installation layout



8. Using of the menus



NOTE: pressure on the keys may be quick (less than 2 s) or prolonged (longer than 2 s). Unless specified otherwise, quick pressure is intended. To confirm the setting of a parameter, prolonged pressing is necessary.

8.1 Switching the display ON and OFF

The procedure to switch on the display is as follows:







• the first level menu is displayed 7

The procedure to switch off the display is as follows:

press the ESC key

NOTE: there is no automatic exit from the WZ quick configuration menu. For all the other menus, the display switches off automatically after 60 seconds of inactivity.

8.2 Navigation keys

• The simultaneous pressing of the \uparrow and ENTER keys produces an opening command.



ullet The simultaneous pressing of the \bigvee and ENTER keys produces a closing command.



 The simultaneous pressing of the ↑ and ↓ keys produces a POWER RESET command (power supply interruption and automation restart).



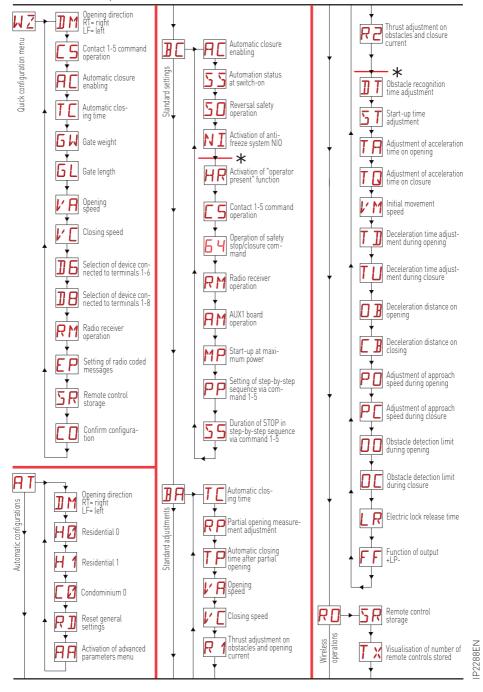
• Keep the UP ↑ or DOWN ↓ key pressed to begin fast menu scrolling.

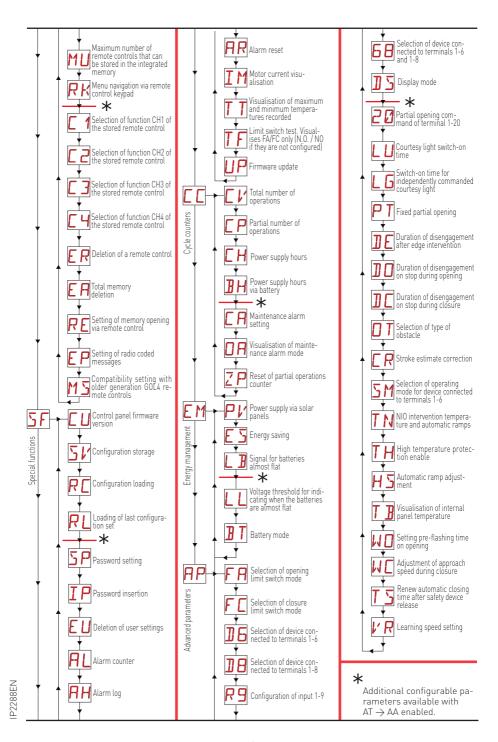
To set a parameter, select the desired value and press ENTER for 2 seconds to save. Example: setting of 30 seconds for parameter TC



 In some menus, the parameter measurement unit can be viewed by pressing the ENTER key once the value has been displayed.

8.3 Menu map





9. Product start-up

For rapid configuration of the product, use the WIZARD (WZ) menu or the second level AT (Automatic Configurations) menu [See par. 13.2].

For detailed, customised configuration, use the main menus BC, BA, RO, SF, CC, EM, AP.

9.1 WZ configuration wizard menu

To access the WZ configuration wizard menu:

Hold down the ENTER button for 2 seconds.

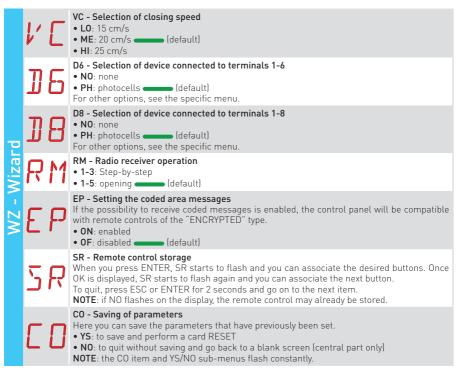
When OK has stopped flashing, DM, the first menu parameter, is displayed.



To set a parameter:

- 1. Press ENTER to access the configuration items.
- 2. Scroll UP/DOWN the possible options.
- To confirm, press the ENTER button for 2 seconds. The selected value flashes and when it has finished, the next parameter appears.





To save the configuration:

In the CO parameter select YS (yes) and press the ENTER button for 2 seconds. When the configuration has been saved, a power reset is automatically performed on the card.



To guit without saving changes:

In the CO parameter select NO and press the ENTER button for 2 seconds.



Or: from any main parameter, press the ESC button for 2 seconds.

Example



NOTES:

- The set values are only stored on the card if they are saved using the CO parameter.
- The CO parameter and YS/NO options flash constantly.
- When a configuration item is confirmed, it automatically moves on to the next parameter.
- You can scroll through the menu parameters using the UP/DOWN buttons.
- There is no automatic timeout function to quit.

10. Commands



You are advised to read paragraph 13 for all the details about the possible adjustments.



WARNING: terminal 30 (common positive for commands) has the same functions as terminal 1, so the commands visualised on the display are indicated with 1-5, 1-3, etc. It is different from terminal 1, however, because of the maximum current that can be dispensed and it is also active when the control panel is in standby $E \hookrightarrow DN$.

Command		Function	Description
30 ————————————————————————————————————	NO	STEP-BY-STEP	When selecting $3 \ \ $
		OPENING	When selecting] [\rightarrow [\rightarrow] . the closure of the contact activates an opening operation.
1 6	NO	CLOSURE	When selecting] [\rightarrow [\dashv \rightarrow] - \dashv , closing the contact activates a closing operation.
1 6	NC	SAFETY STOP	When selecting $\Box \Box \rightarrow \Box \Box \Box \rightarrow \Box \Box$, opening of the safety contact stops and prevents any movement. NOTE : to set different safety contact functions, see the $\Box \Box \Box \Box$ parameter settings.
1 8	NC	CLOSING SAFETY DEVICE	The opening of the safety contact triggers a reversal of the movement (reopening) during the closing operation. When selecting $\mathbb{I} \subset \to S \longrightarrow \mathbb{N}$, the opening of the contact prevents any operation when the automation is idle. When selecting $\mathbb{I} \subset \to S \longrightarrow \mathbb{N}$, the opening of the contact only prevents closure when the automation is idle.
1 6 8	NC	CLOSING/ OPENING SAFETY DEVICE	The opening of the safety contact stops and prevents any movement. NOTE: operation corresponds to that of contact 1-6 with $ PP \to SM \to 0S \ . $
1 20	NO	PARTIAL OPENING	The closure of the contact activates a partial opening operation. Once the automation stops, the partial opening control performs the opposite operation to the one performed before the stop.
1 — t— 20	NC	AUTOMATIC CLOSURE OR STOP	Selecting $\PP \rightarrow 20 \rightarrow 1-2$, the permanent closure of the contact enables automatic closure if $\PC \rightarrow 1-2$. Selecting $\PP \rightarrow 20 \rightarrow 1-9$, the opening of the safety contact causes the movement to stop. NOTE: the flashing light flashes.



WARNING: make a jumper for all NC contacts if not used, or deactivate them via the relative menu.

Terminals with the same number are equal.

10.1 SOFA1-SOFA2 or GOPAVRS self-controlled safety edge

Command		Function	Description
SOFA1-SOFA2 GOPAV		SAFETY TEST	Insert the SOFA1-SOFA2 or GOPAVRS device in the slot for plug-in boards AUX1 or AUX2. If the test fails, an alarm message appears on the display.
1 — t 6	NC	SAFETY STOP	When selecting $PP \rightarrow DF \rightarrow DF$, connect the output contact of the safety device to terminals 1-6 on the control panel (in series with the photocell output contact, if installed).
1 — 1 8	NC	CLOSURE SAFETY DEVICE	When selecting $PP \rightarrow DP \rightarrow DP \rightarrow DP$, connect the output contact of the safety device to terminals 1-8 on the control panel (in series with the photocell output contact, if installed).
1 6 8	NC	CLOSING/OPEN- ING SAFETY DEVICE	When selecting $PP \rightarrow 60 \rightarrow 54$, connect the output contact of the safety device to terminals 1-6-8 on the control panel (in series with the photocell output contact, if installed). If $60 \rightarrow 54$, $160 \rightarrow 54$.

11. Outputs and accessories

Output	Value of accessories	Description
- + 0 1	24V / 0.3A	Power supply to accessories Output for power supply to external accessories. NOTE: the maximum absorption of 0.3A corresponds to the sum of all terminals 1.
	ANTENNA	Input for external antenna GOL148REA or hard-wire antenna, set according to the operating frequency of the receiver module used.
+LP-	24 V / 25 W Max.	Configurable 24 V configurable (default: flashing light) The pre-flashing settings can be selected from the third level menu $\Pi P \rightarrow M \square$ and/or $\Pi P \rightarrow M \square$. To modify the operating mode of the LP output, refer to the selection $\Pi P \rightarrow F F$.
AUX	BIXR2 BIXPR2 LAB9 LAN7S SOFA1 – SOFA2 GOPAVRS	The control panel has a slot for plug-in command and safety cards. The action of the control card can be defined by selecting] \longrightarrow FM . When using slot-in radio boards, remove the RX module. The display will show R \not . WARNING : the plug-in board must be inserted and removed with the power supply disconnected. WARNING : BIXLR42 not compatible with AUX slot.
RADIO RX	ZENRS ZENPRS	The control panel is fitted with a housing for modules of the ZENRS radio receiver type (433.92 MHz). Can be replaced with a module of the ZENPRS radio receiver type (868.35 MHz). When using slot-in radio boards, remove the RX module. The display will show RV. WARNING: the modules must be inserted and removed with the power supply disconnected.

Output	Value of accessories	Description
СОМ	BIXMR2	COM - This allows the functioning configurations to be saved using the function $SF \rightarrow SV$. The saved configurations can be recalled using the function $SF \rightarrow RC$.
		COM - The storage module allows the remote controls to be stored. If the control panel is replaced, the storage module being used can be inserted in the new control panel. WARNING: the storage module must be inserted and removed with the power supply disconnected, and paying attention to the positioning direction.
BAT	SBU	BAT - Battery-powered operation The batteries are kept charged when the power supply is on. If the power supply is off, the panel is powered by the batteries until the power is reestablish or until the battery voltage drops below the safety threshold. The control panel turns off in the last case. WARNING: the batteries must always be connected to the control panel for charging. Periodically check the efficiency of the batteries. NOTE: the operating temperature of the rechargeable batteries is from +5°C to +40°C. For advanced control of battery-powered operation, refer to the menu E.M.

12. Jumper setting

Jumper	Description	OFF	ON
JR1	Display mode selection.	Display mode. Only the values and parameters present can be displayed.	,
Jumper	Description	1 30	1 30
JR5	Selection of power supply - auxiliary board.	AUX1 powered from 0-1. (default)	AUX1 powered from 0-30.

13. Adjustments



NOTE: depending on the type of automation and control panel, some menus may not be available.

13.1 Main menu

Display	Description
NZ	WZ - Wizard Quick configuration menu
AT	AT - Automatic Configurations The menu allows you to manage the automatic configurations of the control panel.
36	BC - Basic Configurations The menu allows you to display and modify the main settings of the control panel.
BA	BA - Basic Adjustments The menu allows you to display and modify the main adjustments of the control panel. NOTE: some settings require at least three operations before they are set correctly.
RO	RO - Radio Operations The menu is used to manage the radio functions of the control panel (alarm management, diagnostics enabling, FW updating).
5F	SF - Special Functions The menu allows you to set the password and manage the special functions in the control panel.
	CC - Cycles Counter The menu allows you to display the number of operations carried out by the automation and manage the maintenance interventions.
EM	EM - Energy Management The menu allows you to display and modify the energy saving settings and adjustments (Green Mode and battery management).
AP	AP - Advanced Parameters The menu allows you to display and modify the advanced settings and adjustments of the control panel (limit switch mode, selection of devices connected to the terminals, disengagement duration adjustments, flashing light adjustments, etc.). NOTE: some settings require at least three operations before they are set correctly.

From the main menu you can access the second level menu as follows:

- Use the and keys to select the required function
- press ENTER to confirm

After confirming the selection, you access the second level menu.

For each function of the main menu, there are also additional configurations that can be viewed by enabling the \bigcap function (see the following paragraph).



NOTE: to check if the parameters have actually been modified, quit the relative parameter and then access it again.

The modifications will take effect from the next operation.

13.2 Second level menu - AT (Automatic Configurations)

	Display	Description	Selections available
AT - Automatic configurations	IM	DM - Direction mode RT-opens to the right LF-open to the left	RTLF
	H 🛭	H0 - Predefined setting, residential use 0 This selection loads predefined values for certain standard parameters AC - enabling of automatic closing :1-2 C5 - step-by-step/opening command operation : Step-by-step RM - remote control operation : Step-by-step AM - AUX plug-in board operation : Step-by-step SS - Selection of automation status at start-up : open	i:
	<u>H 1</u>	H1 - Predefined setting, residential use 1 This selection loads predefined values for certain standard parameters AC - enabling of automatic closing : enabled TC - setting of automatic closing time : 1 minute C5 - step-by-step/opening command operation : Step-by-step RM - remote control operation : Step-by-step AM - AUX plug-in board operation : Step-by-step SS - Selection of automation status at start-up : closed	i:
		CO - Predefined setting, condominium use 0 This selection loads predefined values for certain standard parameters AC - Enabling of automatic closure : enabled TC - setting of automatic closing time : 1 minute C5 - step-by-step/opening command operation : Opening RM - remote control operation : Opening AM - AUX plug-in board operation : Opening SS - Selection of automation status at start-up : closed	it
	RJ	RD - Resetting of general settings (SETTINGS RESET) $ \begin{array}{c} $	
	ЯЯ	AA - Activation of additional configurable parameters for each function of the main menu After activation you can scroll through the third level menus. The third level menus are activated for 30 min.	AAA)

13.3 Second level menu - BC (Basic Configurations)

Basic configurations	Display	Description	Selections available
	AC	AC - Enabling of automatic closure ON - Enabled OF - Disabled 1-2 - Dependent on input 1-2	0N1-2
	55	SS - Selection of automation status at start OP - Open CL - Closed Indicates how the control panel considers the automation at the time of switch-on, or after a POWER RESET command.	OPCL
	50	SO - Enabling of reversal safety contact functioning ON - Enabled OF - Disabled When enabled (ON) with the automation idle, if the contact 1-8 is open, all operations are prevented. When disabled (OF) with the automation idle, if the contact 1-8 is open, opening operations are permitted.	<u>ON</u> OF
BC -	ΝI	NI - Enabling of NIO electronic anti-freeze system ON - Enabled OF - Disabled When enabled (ON), it maintains the efficiency of the motor even at low ambient temperatures. NOTE: for correct operation, the control panel must be exposed to the same ambient temperature as the motors. The intervention temperature for NIO can be set by selecting P→TN.	ON OF

13.3.1Additional BC level parameters that can be configured (available with Π T \to Π Π enabled)

	Displ	.ay	Description	Selec avail	
ations			HR - Enabling of "operator present" function ON - Enabled OF - Disabled NOTE: Set HR \rightarrow ON only if $64 \rightarrow 1$ - 4 and $5 \rightarrow 1$ - 3 .		
	F-{ }	Q	 WARNING: If the OPERATOR PRESENT function is activated, make sure that no-one is near the automation when an opening or closing command is given. The actuation device for the OPERATOR PRESENT function must be placed within the visibility of the guided part but away from the moving parts. It must also be installed at a minimum height of 1.5 m and be placed out of the public's reach. 	ПN	<u>OF</u>
nfigu		5	C5 - Operation of command associated with contact 30-5 1-5 - Step-by-step 1-3 - Opening	1-5	1-3
: - Basic configurations	6	4	64 - Functioning of safety stop/closing command.1-4 - Closing1-6 - Safety stop	- \	1-6
	RI	1	RM - Radio receiver operation 1-5 - Step-by-step 1-3 - Opening	1-5	1-3
BC	Al	1	AM - Operation of AUX1 plug-in control board 1-5 - Step-by-step 1-3 - Opening	1-5	1-3
	111		MP - Start-up at maximum power ON - During start-up it increases the thrust on obstacles to maximum OFF - During start-up, the thrust on obstacles is the one adjusted by R 1-R2.		0F
	P	口	PP - Setting step-by-step sequence from command 1-5. ON - Opening-Stop-Closing-Stop-Opening OF - Opening-Stop-Closing-Opening		OF
	5!	5	S5 - Duration of STOP in step-by-step sequence from command 1-5. ON - Permanent OF - Temporary		OF

13.4 Second level menu - BA (Basic Adjustment)

	Dienley	Description	Selections
	T [Description TC - Setting of automatic closing time [s] It is set with different intervals of sensitivity. • from 0" to 59" with intervals of 1 second • from 1' to 2' with intervals of 10 seconds	available
	R P	RP - Adjustment of partial opening measurement [%] Adjusts the percentage of operation in relation to the total opening of the automation. 10 - Minimum 99 - Maximum	10,99
ent	T P	TP - Setting of automatic closing time after partial opening [s] It is set with different intervals of sensitivity. • from 0" to 59" with intervals of 1 second • from 1' to 2' with intervals of 10 seconds	00·59 11,21
BA - Basic adjustment	ľΑ	VA - Opening speed [cm/s]	10-30
- Basic	ľE	VC - Closing speed [cm/s]	10,30
- BA	R 1	R1 - Adjustment of thrust on obstacles and motor current during opening. [%] The control panel is fitted with a safety device which, when it detects an obstacle: • stops the movement and, if outside the obstacle detection area, performs a disengagement. The obstacle detection area during opening is determined by the type of limit switch installed. If there is no limit switch, it is determined according to the selection	9 9 9
	R2	R2 - Adjustment of thrust on obstacles and motor current during closure. [%] The control panel is fitted with a safety device which, when it detects an obstacle: • reverses the movement during closure operations outside the limit area for detection obstacles:	260

13.4.1 Additional BA level parameters that can be configured (available with Π $T \to \Pi\Pi$ enabled)

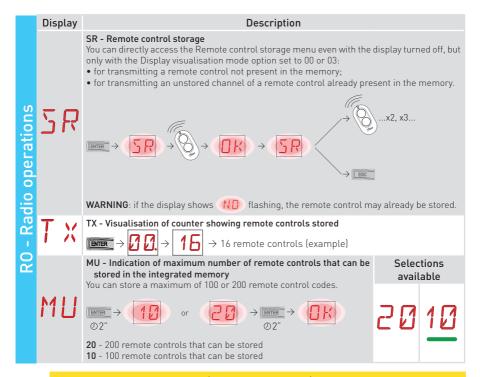
	Display	Description	Selections available
]] T	DT - Adjustment of obstacle recognition time [s/100] 10 - Minimum 60 - Maximum NOTE: the parameter is adjusted in hundredths of a second.	10,50
	5 T	ST - Adjustment of start time [s] 0.5 - Minimum 3.0 - Maximum	0.5·3.0 2.0
	TA	TA - Adjustment of acceleration time during opening [s] 0.5 - Minimum 9.9 - Maximum	Ø.5,9.9 2.0
	TQ	TQ - Adjustment of acceleration time during closure [s] 0.5 - Minimum 9.9 - Maximum	0.5,9.9 2.0
tment	111	VM - Initial movement speed [cm/s] 00 - Minimum 15 - Maximum	00°15
Basic adjustment	T]]	TD - Adjustment of deceleration time during opening [%] Regulates the slope of the deceleration ramp during opening. 10 - Minimum 99 - Maximum	10,99
1	ТШ	TU - Adjustment of deceleration time during closure [%] Regulates the slope of the deceleration ramp during opening. 10 - Minimum 99 - Maximum	10,99
BA		OB - Adjustment of deceleration distance during opening. [cm] Indicates the distance from the end of the opening stroke for the start of the deceleration ramp. 05 - Minimum 99 - Maximum	Ø 5,9 9
		OB - Adjustment of deceleration distance during closing. [cm] Indicates the distance from the end of the closure stroke for the start of the deceleration ramp. 05 - Minimum 99 - Maximum	Ø 5,9 9
	P [PO - Adjustment of approach speed during opening [cm/s] Indicates the speed from the end of the deceleration ramp to the end of the opening stroke 03 - Minimum 10 - Maximum NOTE: gradually increase the approach speed if there is a series of quick vibrations (chattering) in heavy gates installed with a slight incline.	03·10 05
	PC	PC - Adjustment of approach speed during closing [cm/s] Indicates the speed from the end of the deceleration ramp to the end of the closing stroke. 03 - Minimum 10 - Maximum	03·10 05

Basic adjustment	Display	Description		tions lable
	00	00 - Obstacle detection limit during opening [cm] Indicates the distance from the opening stop at which disengagement is deactivated. NOTE: not active if $\PP \rightarrow F \rightarrow \Sigma $ or if $\PP \rightarrow F \rightarrow P $ $\times $.		99
		OC - Obstacle detection limit during closure [cm] Indicates the distance from the closure stop at which reversal is deactivated. NOTE: not active if $\PP \rightarrow F \square \rightarrow \Sigma X$ and if $\PP \rightarrow F \square \rightarrow P X$.	05 <u>4</u>	99
	LR	LR - Electric lock release time [s] If enabled, this indicates the electric lock activation time at the start of every opening operation with the automation closed.	0.5 1	<u>2</u> .5
BA - Basic a	FF	FF - Function of output +LP- 00 - courtesy light 01 - electric lock + release stroke 02 - electric lock + release stroke 03 - ON-OFF flashing light 04 - ON-OFF flashing light for LED without oscillator 05 - fixed light (at 230V AC, or LED with internal oscillator) 06 - proportional indicator light for open gate (with signal of battery operation) 07 - fixed indicator light for open gate (automation not closed) 08 - automation closed (for fail-safe electromagnets) 09 - automation open 10 - automation moving (can also be used for electromagnets that need to be powered throughout the operation) 11 - automation opening 12 - automation closing 13 - maintenance alarm 14 - signal for batteries almost flat 0N - output always active		



NOTE: make adjustments gradually and only after performing at least three complete operations to allow the control panel to be set correctly and detect any friction during operations.

13.5 Second level menu - RO (Radio Operations)



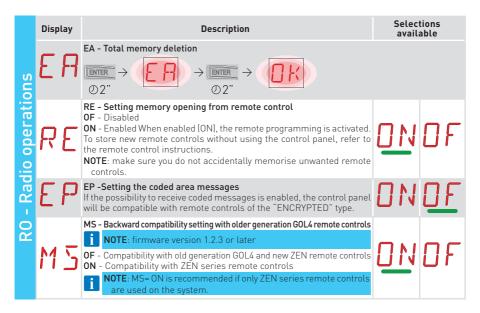


WARNING: selecting $\mu \underline{U} \rightarrow 2\underline{D}$ (200 remote controls), the configurations \underline{U} 1 and \underline{U} 2 saved with the $\underline{S}F \rightarrow \underline{S}V$ command will be lost. This also applies for the last configuration reloaded with RL. In addition, new configurations cannot be saved on \underline{U} 1 and \underline{U} 2.

	Display	Description	Selections available
RO - Radio operations	RK	RK - Menu navigation using remote control keyboard ON - Enabled OF - Disabled With the display turned off, quickly type in the sequence of keys ③ ③ ② ④ ↑ from the stored remote control you want to use. Make sure all the CH keys are stored. WARNING: during navigation with a remote control keyboard ALL the stored remote controls are inactive. 1 [Enter] 2 (Δ) 3 [Esc) 4 (∇) To make viewing and adjustment easier (avoiding the need to continuously press the remote control, press the UP ↑ or DOWN ↓ key once to begin slowly scrolling through the parameters. This scrolling movement is faster if the UP ↑ or DOWN ↓ key is pressed twice. To stop the scrolling, press ENTER. To confirm your choice of parameter, press ENTER again. To test any new setting, switch off the display and issue an opening command using key ③. Navigation using a remote control keyboard is automatically disabled after 4 minutes of inactivity or by setting R ★ → □ F.	ON OF

13.5.1 Additional RO level parameters that can be configured (available with $\mbox{H\ T} \rightarrow \mbox{H\ H}$ enabled)

	Display	Description	Selec avail		
RO - Radio operations	[1 [2	C1, C2, C3, C4 - Selection of CH1, CH2, CH3, CH4 function of stored remote control N0 - No setting selected 1-3 - Opening command 1-4 - Closing command 1-5 - Step-by-step command P3 - Partial opening command L6 - Command to switch the courtesy light on/off 1-9 - STOP command If even just one [any] CH key of the remote control is stored, the opening or step-by-step command is implemented. NOTE: the - Gopening and - Setp-by-step options are available as alternatives, and depend on the selection - M. If 2-4 CH keys of a single remote control are stored, the functions matched in the factory with the CH keys are as follows: CH1= opening/step-by-step command CH2= partial opening command; CH3= courtesy light on/off command CH4= STOP command.	N	- - -	חטום
	FR	ER - Deletion of a single remote control			
	_ ' '	©2"			

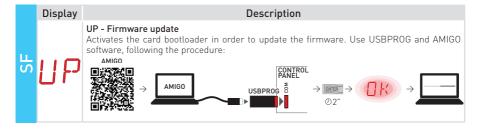


13.6 Second level menu - SF (Special Functions)

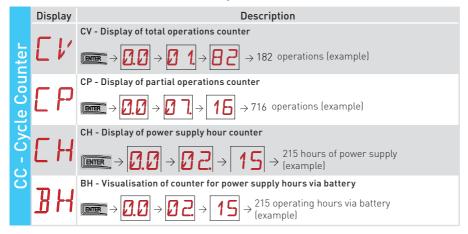
10.	13.0 Second tever mend Si (Special Functions)			
	Display	Description		
SF - Special Functions	СШ	CU - Visualisation of the firmware version on the control panel $\Rightarrow R$. $\Rightarrow R$ Release 1.1 (example)		
	ラ ピ	SV - Saving user configuration on control panel storage module Selections available By selecting RD → MU → 10 you can save up to 2 personalised configurations in memory positions U 1 and U2 only with the storage module present on the		
	۷ <i>۲</i>	warning: if R□ → MU → 20 is selected, no user configuration can be saved on U 1 and U 2. Warning: if the display visualises N□ flashing, the memory module may not be installed.		
	RC	RC - Configuration loading NITER ->		
	RL	RL - Loading of last configuration set ② 2" The control panel automatically saves the last configuration set, and keeps it memorised in the storage module. In the event of a fault or the replacement of the control panel, the last configuration of the automation can be restored by inserting the storage module and loading the last configuration set.		

13.6.1 Additional SF level parameters that can be configured (available with \sqcap \intercal \to \sqcap \sqcap enabled)

	Disp	olay	Description
	5	p	SP - Setting the pass word NOTE: this can only be selected when the password is not set. Setting the password prevents unauthorised personnel from accessing selections and adjustments. You can delete the set password by selecting the sequence JR1=0N, JR1=0FF, JR1=0N.
	Ι	P	IP - Inserting the password Comparison of the password Parison of the password Parison of the password Parison of the password Passw
ctions	Ε	Ц	EU - Deletion of user configurations and last configuration set in the storage module $\underbrace{\text{ENTER}}_{\mathbb{O}2''} \rightarrow \underbrace{\mathbb{O}2''}$
- Special Functions	R	L	AL - Alarm counter Used to view, in sequence, the counters of alarms that have been triggered at least once [alarm code + number of times triggered]. With a and v, you can scroll through all the counters and see all the alarms recorded.
SF - Speci	R	 	AH - Alarm log Used to view, in sequence, alarms that have been triggered [maximum 20]. With and you can scroll through the entire alarm log. The display shows the alarm number and code, alternated. The highest number corresponds to the most recent alarm and the lowest number (0) corresponds to the oldest alarm.
0,	R	R	AR - Alarm reset Resets all the alarms in the memory (counters and log). O 2" NOTE: when the installation has been completed, you are advised to delete the alarms in order to facilitate future checks.
	I	M	IM - Motor current visualisation
	T	T	TT - Display min / max temperatures recorded • by pressing for 2 seconds the values are reset • minimum value with active right point
	T	F	TF - Limit switch test Only FA / FC are displayed when the respective limit switches are configured and active. If the limit switches are active but not configured: • FA = N.O. (both active points) • FC = NO (no active point)



13.7 Second level menu - CC (Cycles Counter)



13.7.1 Additional CC level parameters that can be configured (available with Π $T \to \Pi$ enabled)

	Display	Description	Selections available
CC - Cycles counter	EЯ	CA - Setting the maintenance alarm (factory setting - alarm deactivated: 0.0 00. 00) You can set the required number of operations (regarding the partial operations of signalling the maintenance alarm. When the set number of operations is reached message appears on the display Example: Setting the maintenance alarm after 700 operations (00) (07) (00)	, the alarm
	0 A	OA - Selecting maintenance alarm display mode 00 - Visualisation on display (alarm message 1/2) 01 - Visualisation on flashing light (with the automation idle, 4 flashes are made and then repeated every hour) and on display (alarm message 1/2). 02 - Visualisation on "open gate" indicator light (with the automation closed, 4 flashes are made and then repeated every hour) and on display (alarm message 1/2).	
	ZP	ZP - Reset of partial operations counter ⊕□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□	

13.8 Second level menu - EM (Energy Management)

	Display	Description	Select avail		
+	PV	PV - Solar panel power supply (panels not supplied) ON - Enabled OF - Disabled			F
		ES - Energy-saving (disconnection of accessories connected to terminals 0-1 when the automation is in standby) ON - Enabled (the red point on the right of the display flashes every 5 s. Output +LP- is managed only for courtesy light). OF - Disabled Power supply disconnection mode is activated after 15 s with the gate closed, or when the gate is idle and automatic closure is not enabled. The automation resumes its normal operation when a command is received on the radio board (ZENRS-ZENPRS) or following a contact 30-5, 30-20. WARNING: if you use accessories that need to remain powered even with Energy Saving is enabled (e.g. LAN4 or GOPAV), set the jumper JR5 relating to the slot used on power supply 0-30.	ΠN	<u> </u>	<u>-</u>
2	LB	LB - Indication that batteries are almost flat 00 - Visualisation on display (alarm message) 01 - Visualisation on flashing light (with the automation idle, 2 flashes are made and then repeated every hour) and on display (alarm message) 02 - Visualisation on "open gate" indicator light (with the automation closed, 2 flashes are made and then repeated every hour) and on display (alarm message)			1

13.8.1 Additional EM level parameters that can be configured (available with \sqcap \intercal \rightarrow \sqcap \sqcap enabled)

Display Descr		Description			tions lable	
agen		LL - Voltage threshold for indicating that batteries are almost flat (V) 17 - Minimum 24 - Maximum	1	7,	⊒ ι -	1
man		NOTE: it is set with an interval of sensitivity of 0.5 V shown when the decimal point on the right lights up.		_2	2	
EM - Energy managemen	BT	BT - Battery mode 00 - Anti-panic (performs the opening operation following a mains supply failure. The automation opens but does not accept any other commands until the mains supply has been restored). 01 - Continuous operation - the last operation performed before control panel switch-off will be an opening. 02 - Continuous operation - the last operation performed before control panel switch-off will be an closure.		10		1

13.9 Second level menu - AP (Advanced Parameters)

	Display	Description	Selections available
AP - Advanced Parameters	FA	FA - Selection of opening limit switch mode NO - None SX - Stop limit switch (after activation, the gate stops its movement) PX - Proximity limit switch (after activation, the gate continues as far as the end stop and any obstacle is considered a stop)	NOPX 5x
	FC	FC - Selection of closing limit switch mode NO - None SX - Stop limit switch (after activation, the gate stops its movement) PX - Proximity limit switch (after activation, the gate continues as far as the end stop and any obstacle is considered a stop)	NOPX 5x
	16	D6 - Selection of device connected to terminals 1-6 N0 - None PH - Photocells P41 - Photocells with safety test SE - Safety edge (if contact 1-6 opens, there is a disengagement of 10 cm after the stop) S41 - Safety edge with safety test (if contact 1-6 opens, after the stop there is a disengagement of a duration depending on the selection RP → JE	' ''
	18	D8 - Selection of device connected to terminals 1-8 N0 - None PH - Photocells P41 - Photocells with safety test SE - Safety edge S41 - Safety edge with safety test	NOPH P415E 541
	R 9	R9 - Enabling automatic closing after command 1-9 (STOP). ON - Enabled OF - Disabled When enabled (ON), after a command 1-9, the automation carries out automatic closing (if enabled), after the set time.	ONOF

Ś	Display	Description		tions able
iced Parameter	6 8	68 - Selection of the device simultaneously connected to terminals 1-6 and 1-8 N0 - None SE - Safety edge S41 - Safety edge with safety test If different from N0, the simultaneous opening of inputs 1-6 and 1-8 causes: • movement stop and reversal during a closing operation • movement stop and disengagement of a duration depending on the selection P→ E during an opening operation	N 0 5 41	5 E
AP - Advanced	1 5	DS - Setting of display visualisation mode 00 - No visualisation 01 - Commands and safety devices with radio test. Display of countdown to automatic closure. 02 - Automation status 03 - Commands and safety devices NOTE: the setting ☑ ↑ allows you to see when a radio transmission is received, for range checks.	0 2	



NOTE: make adjustments gradually and only after performing at least three complete operations to allow the control panel to be set correctly and detect any friction during operations.

13.9.1 Additional AP level parameters that can be configured (available with Π T \to Π Π enabled)

	D: 1		Selections
	Display	Description	available
	20	20 - Partial opening command of terminal 1-20 P3 - Partial opening command 1-2 - Enabling of automatic closure 1-9 - Stop input	P31-2
	LU	LU - Setting the courtesy light switch-on time (s) To enable the parameter, set the selection ∄ → F F as "courtesy light". It is set with different intervals of sensitivity. NO - Disabled • from 01" to 59" with intervals of 1 second • from 1' to 2' with intervals of 10 seconds • from 2' to 3' with intervals of 1 minute ON - Permanently enabled (switched off via remote control) NOTE: the courtesy light switches on at the start of each operation.	NO 0 159 1' 2' 2' 3'
AP - Advanced Parameters	L 6	LG - Switch-on time for independently commanded courtesy light [s] To enable the parameter, set the selection ☐ ☐ → F F as "courtesy light". It is set with different intervals of sensitivity. NO - Disabled • from 01" to 59" with intervals of 1 second • from 1" to 2" with intervals of 10 seconds • from 2" to 3" with intervals of 1 minute ON - Switched on and off with remote control NOTE: the switching on of the light does not depend on the start of an operation, but can be commanded separately using the special remote control key.	
AP-A	PT	PT - Fixed partial opening ON - Enabled OF - Disabled If ON, a partial opening command given on the partial opening position is ignored. With contact 1-20 closed (for example with the timer or manual selector), the gate will partially open. If it is then fully opened (command 1-3) and reclosed (even with automatic closure), it will stop at the partial opening position.	ON OF
	IJΕ	DE - Disengagement setting if an edge is triggered [cm] Regulates the disengagement distance when an edge (active or passive) is triggered during opening or closure. 00 - Deactivated 20 - Maximum	00,20
]0	DO - Setting of disengagement on stop during opening [mm] Regulates the distance of the disengagement on the mechanical opening stop. 00 - Disabled 15 - Maximum NOTE: not active if F → 5 X	0 0 1 5 07
	IC	DC - Setting of disengagement on stop during closure [mm] Regulates the distance of the disengagement on the mechanical opening stop. 00 - Disabled 99 - Maximum NOTE: not active if F □ → 5 X	07 15

	Dis	play	Description	:		tions able	
		i	OT - Selection of type of obstacle identification 00 - Overcurrent or gate stopped 01 - Overcurrent 02 - Door stopped NOTE: the obstacle identification for "door stopped" is faster but more sensitive. CR - Stroke estimate correction [%] DO NOT USE (diagnostic purposes only)			T (1
	L	רז	DO NOT USE (diagnostic purposes only) SM - Selection of operating mode of device connected to terminals 1-6	_	<u>ה</u>		ב ב
AP - Advanced Parameters	5	11	 OB - During the operation, the opening of the safety contact stops the movement (with disengagement if				1 3 5
	T	11	TN - Setting of intervention temperature for the NIO electronic anti- freeze system and automatic HS ramps [°C] This value does not refer to the ambient temperature, but to the internal control panel temperature.		9	5	
A	T		TH - High temperature protection enable If ON, the automatic reclosing time is extended when the maximum switchboard temperature is reached. If the condition persists, all the controls are disabled.		N		F
	Н	5	HS - Automatic ramp adjustment ON - Enabled OF - Disabled When enabled (ON), at low ambient temperatures the start time ST increases up to the maximum value and the acceleration time T and T diminishes to the minimum value. NOTE: for correct operation, the control panel must be exposed to the same ambient temperature as the motors. The intervention temperature can be set with the selection P→T N.	0	N		<u>F</u>
	T	R	TB - Permanent display of the internal control panel temperature [°C]		N		F
	11		WO - Setting of pre-flashing time on opening [s] Adjustment of the lead time for the switch-on of the flashing light, in relation to the start of the opening operation from a voluntary command. 00 - Minimum 05 - Maximum			00	5

ers	Display	Description	Selections available
Parameters	NC	WC - Setting of pre-flashing time on closing [s] Adjustment of the lead time for the switch-on of the flashing light, in relation to the start of the closing operation from a voluntary command. 00 - Minimum 05 - Maximum	00"
- Advanced	T 5	TS - Setting of renewal of automatic closing time after PH safety device release [%] 00 - Minimum 99 - Maximum	00,99
AP - Ac	V R	VR - Setting of learning speed [cm/s]	05·10 <u>*</u>

14. Signals visualised on the display

NOTE: depending on the type of automation and control panel, certain visualisations may not be available.

14.1 Display of automation status

NOTE: the automation status display mode is only visible with Display visualisation mode set to 02.



Display	Description		
]M▶RT		
][Automation closed		
Automation closed Release door open			
Automation open			
Automation open Release door open			
	Automation stopped in intermediate position		
٦.	Automation stopped in intermediate position Release door open		
0 1	Automation closing		
1	Automation that slows down during closing.		
Automation opening			
	Automation that slows down during opening.		

Display	Description
	IM>LF
_	Automation closed
	Automation closed Release door open
	Automation open
	Automation open Release door open
]	Automation stopped in intermediate position
] .	Automation stopped in intermediate position Release door open
0 0	Automation closing
	Automation that slows down during closing.
11	Automation opening
1	Automation that slows down during opening.

14.2 Display of safety devices and commands

NOTE: the safety device and command display mode is only visible with Display visualisation mode set at 01 or 03.

AP > 15 > 0 1	AP > 15 > 03
---------------	--------------

Display	Description	Display	Description
1-2	1-2 - Automatic closing activation com- mand	68	68 - Selection of the device simultaneously connected to terminals 1-6 and 1-8
1-3	1-3 - Opening command	1-5	1-6 - Safety device with opening and closing stop
1-4	1-4 - Closing command	5 1.	S1 Detection of stop during closure
1-5	1-5 - Step-by-step command	1-8	1-8 - Safety with closing reversal
P3	P3 - Partial opening command.	1-9	1-9 - STOP command
48	4P - Closing command with operator present	3P	3P - Opening command with operator present
RX	RX - Radio reception (of any memorised key of a transmitter present in the memory)	52.	S2 Detection of stop during opening
	NX - Radio reception (of any non-memorised key)		00 Obstacle detection area reached during opening
NX	NOTE: with the selection ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐	Ο C.	OC. Obstacle detection area reached during closure
ΕX	EX - Rolling-code radio reception out of sequence	RV	RV - Enabling/disabling of built-in radio receiver via RX
EP	EP - Radio reception not complying with the parameter configuration \bigcirc \bigcirc \rightarrow \bigcirc \bigcirc	MQ	MQ - Learning operation of mechanical end stops in progress
ΕX	CX - Command received from AUX1 board	HT	HT - Heating of the motors (NIO function) in progress
F C.	FC Closure limit switch	H5	HS - Sharp NIO start-up
FA.	FA Opening limit switch	ا ا	JR1 - Variation of the JR1 jumper status
211	SW - Release door open. When the release door is closed, the control panel performs a RESET (alarm) \(\). It is possible to ignore the reset by holding down the ESC & DOWN keys for 3 seconds until the SW stops flashing. If the RESET is disabled, make sure not to move the gate manually. NOTE: If you return to the menu, the reset	AV	AV - Function anti-violation.
	is reactivated.		

14.3 Visualisation of alarms and faults



WARNING: the visualisation of alarms and faults is possible with any visualisation selection. The signalling of alarm messages takes priority over all other displays.

Type of alarm	Display	Description	Operation
Mechanical alarm	EM	M3 - Automation blocked	Check the mechanical parts.
	MH	M4 - Motor short circuit	Check connection of motor.
	MB	M8 - Stroke too long	Check the rack / chain belt
	M9	M8 - Stroke too short	Manually check that the gate moves freely.
	MB	MB - Absence of motor during an operation	Check connection of motor.
	ΜIJ	limit switch If the limit switch is configured but can't be found, each stop (from the OB decelera- tion start point) is seen as an obstacle and indicated with MD.	Check connection of the opening limit switch.
	ME	ME - Irregular operation of the closure limit switch If the limit switch is configured but can't be found, each stop (from the CB deceleration start point) is seen as an obstacle and indicated with ME.	Check connection of the closure limit switch.
	MI	MI - Detection of fifth consecutive obstacle	Check for the presence of permanent obstacles along the stroke of the automation.
	ML	ML - Inverted limit switches	Check the positioning and connection of the limit switches. Also check the motor connection.
		OD - Obstacle during opening	Check for the presence of obstacles along the automation stroke.
	OE	OE - Obstacle during closure	Check for the presence of obstacles along the automation stroke.
	OF	OF - Automation blocked on opening	Check the mechanical parts and make sure there are no obstacles along the automation stroke.
	06	OG - Automation blocked on closure	Check the mechanical parts and make sure there are no obstacles along the automation stroke.
Power supply Settings	56	S6 - Incorrect setting of safety device test	Check the configuration of parameters $16.10.60$. If $60 \rightarrow 54$, 16 and 10 cannot be 94 or 54 .
Service	V O	V0 - Request for maintenance intervention	Proceed with the scheduled maintenance intervention.

Type of			
alarm	Display	Description	Operation
Radio operations alarm	R Ø	R0 - Insertion of a storage module containing over 100 stored remote controls WARNING: the Rロ→Mレーング setting is made automatically.	To save the system configurations on the storage module, delete any stored remote controls and bring the total to less than 100. Set $\mathbb{R} \ \square \to \mathbb{M} \ \square \to \mathbb{1} \ \square$.
	R3	R3 - Storage module not detected	Insert a storage module.
	RH	R4 - Storage module not compatible with the control panel	
	R5	R5 - No serial communication with the storage module	Replace the storage module.
	R5	R6 - Insertion of a specific storage module for testing	
Power supply alarm	PØ	P0 - No mains voltage	Check the control panel is powered correctly. Check the line fuse. Check the mains power supply.
	P 1	P1 - Microswitch voltage too low	Check the control panel is powered correctly.
Battery alarm	BØ	B0 - Battery almost flat	Check battery voltage. Replace battery.
Accessories alarm	RØ	AO - Failure of test of safety sensor on contact 6	Check the device SOFA1-A2 is working correctly. If the supplementary SOF board is not inserted, check the safety test is disabled.
	R 1	A1 - Simultaneous safety sensor test on contacts 6 and 8 failed	Check the wiring and correct operation of the safety sensor.
	R 3	A3 - Failure of test of safety sensor on contact 8	correctly. If the supplementary SOF board is not inserted, check the safety test is disabled.
	87	A7 - Incorrect connection of contact 9 to terminal 41	Check that terminal 1 and 9 are correctly connected.
	89	A9 - Overload on output +LP-	Check the device connected to output +LP- is working properly.

15. Troubleshooting

Problem	Possible cause	Alarm signalling		Operation
The control panel does not switch on	No power supply.			Check the power supply cable and the relative wiring
The automation does not open or	No power.			Check power supply cable.
close.	Short circuited accessories	I5		Disconnect all accessories from terminals 0-1 (a voltage of 24V= must be present) and reconnect them one at a time. Contact Technical Service
	Blown line fuse.			Replace fuse.
	Safety contacts are open.	1-6 68	1-8	Check that the safety contacts are closed correctly (NC).
	Safety contacts not correctly connected or self-controlled safety edge not functioning correctly.	A 0 A 1 A 3	1-6 1-8 68	Check connections to terminals 6-8 on control panel and connections to the self-controlled safety edge.
	Photocells activated.	1-6	1-8	Check that the photocells are clean and operating correctly.
	The automatic closure does not work.			Issue any command. If the problem persists, contact Technical Service
	Motor fault	M		Check motor connection, if the problem persists, contact Technical Service.
	Mechanical fault	M		Check the rack and transmission chain, and/or the mechanical parts.
	Release microswitch open	5	N	Check that the hatch is closed correctly and the microswitch makes contact.
	Faulty control panel	IT IB IB IB	IE IM IO IR	Contact Technical Service
	Both limit switches are active.	F F	R. C.	Check the connection of the limit switches.
The external safety devices are not activated.	Incorrect connections between the photocells and the control panel.			Check that I- 6 / I- 1 is displayed Connect NC safety contacts together in series and remove any jumpers on the control panel terminal board.
				Check the setting of $PP \rightarrow B$ and $PP \rightarrow B$.
opens/closes briefly and then	There is a presence of friction.	M M T	9	Manually check that the automation moves freely and check the R 1/R2 adjustment
stops.			_	Contact Technical Service

Problem	Possible cause	Alarm signalling	Operation
has limited range	The radio transmission is impeded by metal structures and reinforced concrete walls.		Install the antenna outside.
with the automation moving.			Replace the transmitter batteries.
The remote control does not work	No storage module or incorrect storage module.	RØ	Switch the automation off and plug in the correct storage module.
		R3 R5	Check the correct memorisation of the transmitters on the built-in radio. If there is a fault with the radio receiver that is built into the control panel, the remote control codes can be read by removing the storage module.
The flashing light is not working	The wires of the flashing light are detached or have short circuited.	A9	Check the connections. If the problem persists, contact Technical Service.

All the rights concerning this material are the exclusive property of ASSA ABLOY Entrance Systems AB. Although the contents of this publication have been drawn up with the greatest care, ASSA ABLOY Entrance Systems AB cannot be held responsible in any way for any damage caused by mistakes or omissions in this publication. We reserve the right to make changes without prior notice.

Copying, scanning or changing in any way is expressly forbidden unless authorised in writing by ASSA ABLOY Entrance Systems AB.

The crossed-out wheelie bin symbol indicates that the product should be disposed of separately from normal household waste. The product should be recycled in accordance with local environmental regulations for waste disposal. By separating a product marked with this symbol from household waste, you will help reduce the volume of waste sent to incinerators or land-fill and minimise any potential negative impact on human health and the environment.

